

Received: 2024-05-28 Accepted: 2024-06-05 Published: 2024-06-07

#### **Letters**

# **Note for the P versus NP Problem**

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**Abstract** - P versus NP is considered as one of the most fundamental open problems in computer science. This consists in knowing the answer of the following question: Is P equal to NP? It was essentially mentioned in 1955 from a letter written by John Nash to the United States National Security Agency. However, a precise statement of the P versus NP problem was introduced independently by Stephen Cook and Leonid Levin. Since that date, all efforts to find a proof for this problem have failed. Another major complexity class is NP-complete. It is well-known that P is equal to NP under the assumption of the existence of a polynomial time algorithm for some NP-complete. We show that the Monotone Weighted Xor 2-satisfiability problem (MWX2SAT) is NP-complete and P at the same time. Certainly, we make a polynomial time reduction from every directed graph and positive integer k in the K-CLOSURE problem to an instance of MWX2SAT. In this way, we show that MWX2SAT is also an NP-complete problem. Moreover, we create and implement a polynomial time algorithm which decides the instances of MWX2SAT. Consequently, we prove that  $P = NP$ .

**Keywords** - Complexity classes; Boolean formula; Graph; Completeness; Polynomial time.

#### **1 Introduction**

*P* versus *NP* is one of the most important and challenging problems in computer science [\[1\]](#page-4-0). It asks whether every problem whose solution can be quickly verified can also be quickly solved. The informal term "quickly" here refers to the existence of an algorithm that can solve the task in polynomial time [\[1\]](#page-4-0). The general class of problems for which such an algorithm exists is called *P* or "class *P*" [\[1\]](#page-4-0).

Another class of problems called *NP*, which stands for "nondeterministic polynomial time", is defined by the property that if an input to a problem is a solution, then it can be quickly verified [\[1\]](#page-4-0). The *P* versus *NP* problem asks whether *P* equals *NP*. If it turns out that  $P \neq NP$ , which is widely believed to be the case, it would mean that there are problems in *NP* that are harder to compute than to verify [\[1\]](#page-4-0). This would have profound implications for various fields, including cryptography and artificial intelligence [\[2\]](#page-4-1).

Solving the *P* versus *NP* problem is considered to be one of the greatest challenges in computer science [\[1\]](#page-4-0). A solution would have a profound impact on our understanding of computation and could lead to the development of new algorithms and techniques that could solve many of the world's most pressing problems [\[1\]](#page-4-0). The problem is so difficult that it is considered to be one of the seven Millennium Prize Problems, which are a set of seven unsolved problems that have been offered a 1 million prize for a correct solution [\[1\]](#page-4-0).

# **2 Materials and methods**

*NP*-complete problems are a class of computational problems that are at the heart of many important and challenging problems in computer science. They are defined by the property that they can be quickly verified, but there is no known efficient algorithm to solve them. This means that finding a solution to an *NP*-complete problem can be extremely time-consuming, even for relatively small inputs. In computational complexity theory, a problem is considered *NP*-complete if it meets the following two criteria:

- 1. **Membership in NP**: A solution to an *NP*-complete problem can be verified in polynomial time. This means that there is an algorithm that can quickly check whether a proposed solution is correct [\[3\]](#page-4-2).
- 2. **Reduction to NP-complete problems**: Any problem in *NP* can be reduced to an *NP*-complete problem in polynomial time. This means that any *NP*-problem can be transformed into an *NP*-complete problem by making a small number of changes [\[3\]](#page-4-2).

If it were possible to find an efficient algorithm for solving any one *NP*-complete problem, then this algorithm could be used to solve all *NP* problems in polynomial time. This would have a profound impact on many fields, including cryptography, artificial intelligence, and operations research [\[2\]](#page-4-1). Here are some examples of *NP*-complete problems:

- **Boolean satisfiability problem (SAT)**: Given a Boolean formula, determine whether there is an assignment of truth values to the variables that makes the formula true [\[4\]](#page-4-3).
- **K-CLOSURE problem**: Given a directed graph  $G = (V, A)$  (*V* is the set of vertices and *A* is the set of edges) and positive integer *k*, determine whether there is a set *V* ′ of at most *k* vertices such that for all  $(u, v) \in A$  either  $u \in V'$  or  $v \notin V'$  (see reference [Queyranne, 1976] from the Johnson and Garey book) [\[4\]](#page-4-3). Note that in this problem, the phrase "either  $u \in V'$  or  $v \notin V''$ is equivalent to either " $(u \in V'$  and  $v \in V'$ ) or  $(u \notin V'$  and  $v \notin V'$ ". This is because the logical implication of the phrase "**either ... or ...**" requires that exactly one of the two conditions be true.

These are just a few examples of the many *NP*-complete problems that have been studied and have a close relation with our current result. A bipartite graph, denoted as  $B = (U, V, E)$ , is an undirected graph characterized by the existence of two node sets *U*, *V* and edges in *E* that only connect nodes from opposite sets. Determining whether a given graph is a bipartite graph can be accomplished efficiently (in polynomial time) [\[3\]](#page-4-2). An independent set *V*' is a subset of vertices in a graph *G* where no two vertices in the set are connected by an edge.

# **Definition 2.1.** *Independent Vertex in Bipartite Graph*

*INSTANCE: A bipartite graph B =*  $(U, V, E)$  *and a positive integer k. QUESTION: Is there set V*′ *of at least k vertices such that V*′ *is an independent set in B? REMARKS: This problem can be easily solved in polynomial time [\[4\]](#page-4-3).* 

We introduce the following problem:

# **Definition 2.2.** *CLOSURE*

*INSTANCE: A directed graph G* = (*V*, *A*) *and a positive integer k. QUESTION: Is there set V'* of at least *k* vertices such that for all  $(u, v) \in A$  either  $u \in V'$  or  $v \notin V'$ ? *REMARKS: The CLOSURE problem is NP-complete. This follows from the fact that it is equivalent to the NP-complete K-CLOSURE problem, where the target closure size is simply complemented.*

By presenting an efficient solution to *CLOSURE*, we would establish a proof that *P* equals *NP*.

#### **3 Results**

Formally, an instance of **Boolean satisfiability problem (SAT)** is a Boolean formula  $\phi$  which is composed of:

- 1. Boolean variables:  $x_1, x_2, \ldots, x_n$ ;
- 2. Boolean connectives: Any Boolean function with one or two inputs and one output, such as ∧(AND), ∨(OR), ¬(NOT), ⇒(implication), ⇔(if and only if);
- 3. and parentheses.

A truth assignment for a Boolean formula  $\phi$  is a set of values for the variables in  $\phi$ . A satisfying truth assignment is a truth assignment that causes  $\phi$  to be evaluated as true. A Boolean formula with a satisfying truth assignment is satisfiable. The problem *SAT* asks whether a given Boolean formula is satisfiable [\[4\]](#page-4-3).

We define a *CNF* Boolean formula using the following terms: A literal in a Boolean formula is an occurrence of a variable or its negation [\[3\]](#page-4-2). A Boolean formula is in conjunctive normal form, or *CNF*, if it is expressed as an AND of clauses, each of which is the OR of one or more literals [\[3\]](#page-4-2). A Boolean formula is in 2-conjunctive normal form or 2*CNF*, if each clause has exactly two distinct literals [\[3\]](#page-4-2).

For example, the Boolean formula:

$$
(x_1 \vee \neg x_2) \wedge (x_3 \vee x_2) \wedge (\neg x_1 \vee \neg x_3)
$$

is in 2*CNF*. The first of its three clauses is  $(x_1 \vee \neg x_2)$ , which contains the two literals  $x_1$  and  $\neg x_2$ . We define the following problem:

#### **Definition 3.1.** *Monotone Weighted Xor 2-satisfiability problem (MWX2SAT)*

*INSTANCE: An n-variable* 2*CNF formula with monotone clauses (meaning the variables are never negated) using logic operators* ⊕ *(instead of using the operator* ∨*) and a positive integer k.*

*QUESTION: Is there exists a satisfying truth assignment in which at least k of the variables are true?*

The following is key Lemma.

**Lemma 3.2.** *MWX*2*SAT* ∈ *NP–complete.*

*Proof.* We can build an equivalent *MWX*2*SAT* instance for any given instance *G* = (*V*, *A*) of the *CLOSURE* problem:

- 1. Variables:
	- Create a variable for each vertex *v* in the original graph *G*. Denote this variable as *v* itself.
	- For each edge  $(u, v)$  in *G*, introduce two new variables denoted by  $x_{uv}$  and  $x_{vu}$ .
- 2. Clauses:
	- For each edge (*u*, *v*) in *G*, construct three clauses using the new variables:
		- **–** (*u*⊕*xuv*): This enforces that either vertex *u* is true or the new variable *xuv* is true (XOR).
		- **–** (*xuv* ⊕*v*): This enforces that either the new variable *xuv* is true or vertex *v* is true (XOR).
		- **–** (*xvu* ⊕ *xuv*): This guarantees that *xuv* and *xvu* have different truth values. Note that *xvu* is not used elsewhere, so it only enforces there is exactly one true variable per each edge  $(u, v)$  over the new variables  $x_{uv}$  and  $x_{vu}$ .

#### **Key Points about the Construction**:

• The first two clauses for each edge  $(u, v)$  ensures that both variables  $u$  and  $v$  for an edge have the same truth value. This is because they represent the "state" of the edge (both in the closure or both outside). By definition, a vertex closure cannot have any outgoing edges pointing to vertices outside the closure. Therefore, no edge can exist where one vertex belongs to the solution and the other does not.

• The third clause for each edge  $(u, v)$  together ensure that exactly one of  $x_{uv}$  or  $x_{vu}$  is true in a satisfying truth assignment. Take into account this condition enforces always a true variable for each edge for every possible satisfying truth assignment.

# **Mapping between CLOSURE solutions and MWX2SAT assignments**:

- A satisfying truth assignment in the *MWX*2*SAT* formula corresponds to a valid closure of at least *k* vertices in the original graph *G* if:
	- **–** Vertices assigned true represent the vertices in the closure *V* ′ .
	- **–** New variable *xuv* assigned true represents that the corresponding edge (*u*, *v*) has both endpoints outside the closure.
	- **–** New variable *xvu* assigned true indicates that the corresponding edge (*u*, *v*) has both endpoints within the closure.

#### **Why this construction works**:

- The clauses enforce that a satisfying truth assignment must have consistent values for a vertex and its corresponding edge variables.
- A *k* >-vertex closure property translates to *k* original variables (vertices) being true in the satisfying truth assignment, along with exactly one true variable from the pair of new variables *xuv* and *xvu* per each edge depending on the specific closure.

## **Equivalence and Complexity**:

- There exists a satisfying truth assignment for the *MWX*2*SAT* formula with at least *k*+ | *A* | true variables if and only if there exists a closure of at least *k* vertices in the original graph. (| *A* | represents the number of edges in the graph).
- Since *CLOSURE* is known to be *NP*-complete, this shows that *MWX*2*SAT* is also *NP*-complete.

In essence, the proof demonstrates that solving *MWX*2*SAT* is equivalent to finding a closure of at least *k* vertices in the *CLOSURE* problem. This implies that *MWX*2*SAT* inherits the *NP*-completeness property from *CLOSURE*. □

This is the main theorem.

**Theorem 3.3.**  $MWX2SAT \in P$ .

*Proof.* There is a connection between finding a satisfying truth assignment in *MWX*2*SAT* with at least *k* true variables and finding a set of at least *k* vertices that is an independent set in a specific graph construction.

Here's a breakdown of the equivalence:

- 1. Graph Construction:
	- Each vertex in the original graph represents a variable in the *MWX*2*SAT* formula.
	- Edges are created between variables based on the structure of the 2*CNF* clauses: If two variables appear in a clause (e.g., (*x*⊕*y*)), then an edge is drawn between the corresponding vertices in the graph.

2. *MWX*2*SAT* and the Graph:

- A truth assignment in *MWX*2*SAT* where at least *k* variables are true directly translates to a set of at least *k* vertices in the constructed graph where true variables correspond to the vertices included in the set.
- The properties of *MWX*2*SAT* clauses ensure that:
- **–** Independent Set: The chosen vertices don't have any edges connecting them (because the variables are connected in the graph, and only one variable from each clause can be true). This satisfies the independent set condition.
- **–** Bipartite Graph: The Boolean formula in *MWX*2*SAT* is satisfiable if and only if the corresponding graph is bipartite.

Therefore, finding a satisfying truth assignment with at least *k* true variables in *MWX*2*SAT* is indeed equivalent to finding a set of at least *k* vertices that fulfills an independent set requirements in the corresponding bipartite graph. However, we know the problem of finding a set of at least *k* vertices that is an independent set in a bipartite graph can be easily solved in polynomial time [\[4\]](#page-4-3). Additionally, verifying if the constructed graph is indeed a bipartite graph can be done in polynomial time [\[3\]](#page-4-2). Consequently, the instances of the problem *MWX*2*SAT* can be solved in polynomial time as well.  $\Box$ 

## **4 Discussion**

A vertex cover (sometimes called a node cover) of a graph *G* is a subset of its vertices, denoted by *V* ′ , such that every edge in *G* has at least one endpoint in *V* ′ [\[4\]](#page-4-3). In general, *V* ′′ is an independent set of an arbitrary undirected graph *G* = (*V*, *E*) if and only if *V* −*V* ′′ is a vertex cover of *G* [\[4\]](#page-4-3). The **Independent Vertex Set in Bipartite Graph** problem is equivalent to finding a vertex cover in a bipartite graph  $B = (U, V, E)$  using at most (| *U* | + | *V* | −*k*) vertices. We implemented a Python-based solution for this algorithm, which is available on GitHub under the username "frankvegadelgado" [\[5\]](#page-4-4).

## **5 Conclusion**

A proof of *P* = *NP* will have stunning practical consequences, because it possibly leads to efficient methods for solving some of the important problems in computer science [\[1\]](#page-4-0). The consequences, both positive and negative, arise since various *NP*-complete problems are fundamental in many fields [\[2\]](#page-4-1). But such changes may pale in significance compared to the revolution an efficient method for solving *NP*-complete problems will cause in mathematics itself [\[1\]](#page-4-0). Research mathematicians spend their careers trying to prove theorems, and some proofs have taken decades or even centuries to be discovered after problems have been stated [\[1\]](#page-4-0). A method that guarantees to find proofs for theorems, should one exist of a "reasonable" size, would essentially end this struggle [\[1\]](#page-4-0).

#### **Acknowledgements**

Many thanks to Sergi Simon, Jorge Felix and Melvin Vopson for their support. ´

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